

# Dichotomous Markov Noise Technique to Model Wind Power Uncertainty in Microgrid Operation

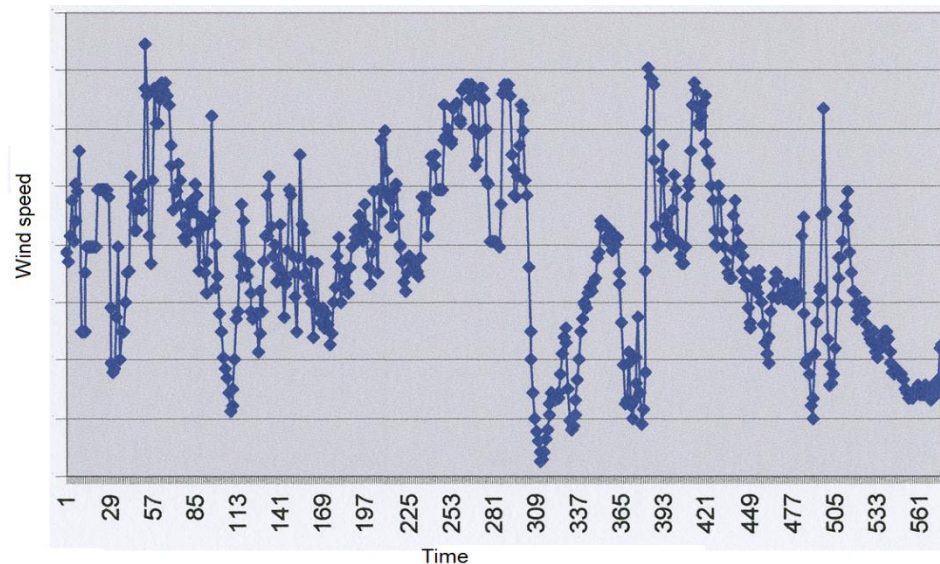
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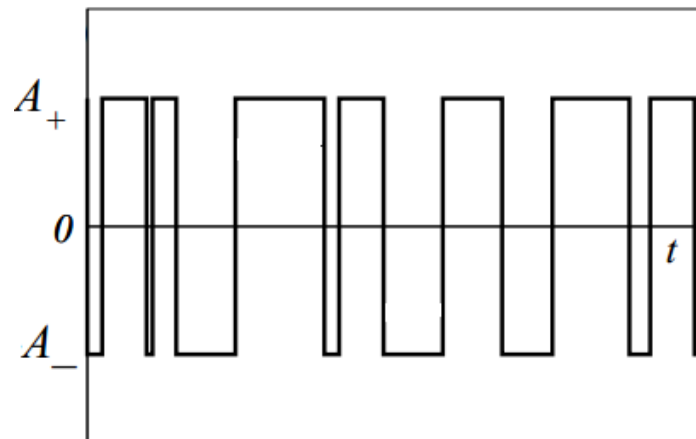
# Introduction

- Probabilistic behavior of the wind power generation brings many challenges in power systems operation and control.
- How to model wind power uncertainty?
- How if there is no PDF and we have only actual hourly wind speed forecast?
- How about in hour-ahead system scheduling?



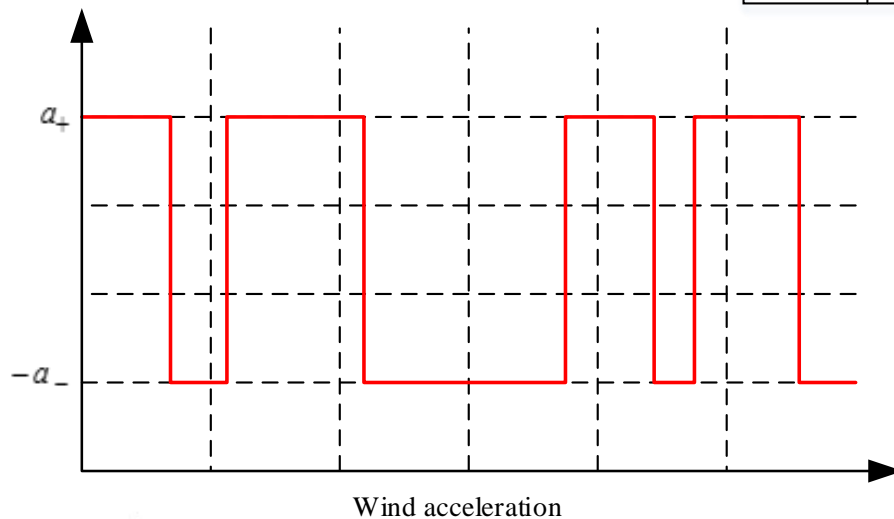
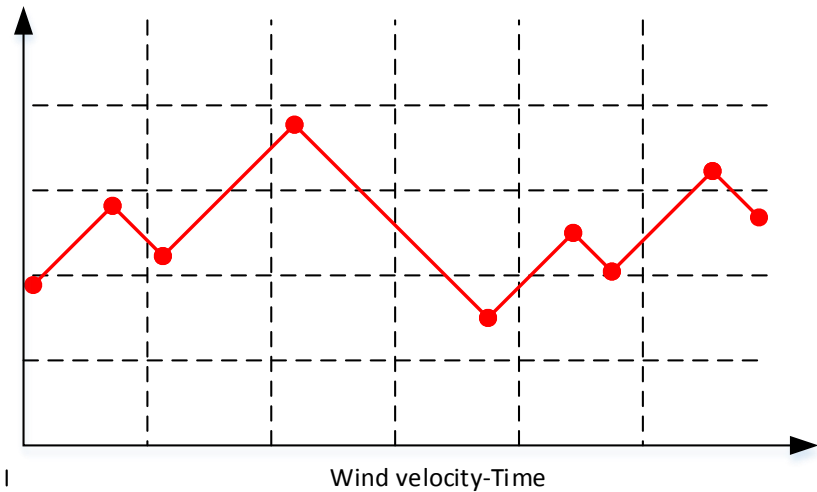
# Dichotomous Markov Noise

- Dichotomous Markov Noise (DMN) is defined as a two-valued stochastic process with the state space values  $A_{\pm}$  with constant transition frequencies of  $f_{\pm}$ , for the increase (+) and decrease rate (−) with the appropriate probabilities  $p_{\pm}(t)$ .
- The switches of  $a(t)$  are Poisson process.



# Dichotomous Markov Noise

Wind velocity



Wind acceleration

# Dichotomous Markov Noise

- Differential equations

$$\frac{d}{dt} \begin{pmatrix} p_+ \\ p_- \end{pmatrix} = \begin{pmatrix} -f_+ & f_- \\ f_+ & -f_- \end{pmatrix} \begin{pmatrix} p_+ \\ p_- \end{pmatrix}$$

- By using the initial values  $p_+(0)=1$  and  $p_-(0)=0$ , the solutions are calculated as follows:

$$p_+(t) = \frac{f_-}{f_- + f_+} + \frac{f_+}{f_- + f_+} e^{-(f_- + f_+)t}$$

$$p_-(t) = \frac{f_+}{f_- + f_+} - \frac{f_-}{f_- + f_+} e^{-(f_- + f_+)t}$$

# Dichotomous Markov Noise

- Defining the average acceleration as:

$$\bar{a}(t) = a_+ p_+(t) - a_- p_-(t)$$

- The average acceleration and the equilibrium point can be calculated as:

$$\bar{a}(t) = \frac{a_+ f_- - a_- f_+}{f_- + f_+} \left( 1 - e^{-(f_- + f_+)t} \right) + v_+ e^{-(f_- + f_+)t}$$

- Thus the equilibrium point of the system is characterized by

$$\lim_{t \rightarrow \infty} \bar{a}(t) = A = \frac{a_+ f_- - a_- f_+}{f_- + f_+}$$

# Microgrid Operation

- Minimizing operating cost

$$\text{Min } OC = \sum_{\forall i} F(P_i) + \lambda P_{u,m}$$

S.t.

$$P_{Gb} - P_{Db} = P_b(\theta, V) \quad \forall b$$

$$Q_{Gb} - Q_{Db} = Q_b(\theta, V) \quad \forall b$$

$$P_i^{\min} \leq P_i \leq P_i^{\max} \quad \forall i$$

$$Q_i^{\min} \leq Q_i \leq Q_i^{\max} \quad \forall i$$

$$Q_C^{\min} \leq Q_C \leq Q_C^{\max} \quad \forall C$$

$$V_b^{\min} \leq V_b \leq V_b^{\max} \quad \forall b$$

$$|S_l(\theta, V)| \leq S_l^{\max} \quad \forall l$$

# Microgrid Operation

- Minimizing Energy Loss

$$\text{Min } EL = \sum_{\forall i} P_{Gi} - \sum_{\forall b} P_{Db}$$

- Minimizing Voltage Profile Deviation

$$\text{Min } VPD = \sqrt{\sum_{\forall b} (V_b - V_{b,desire})^2}$$



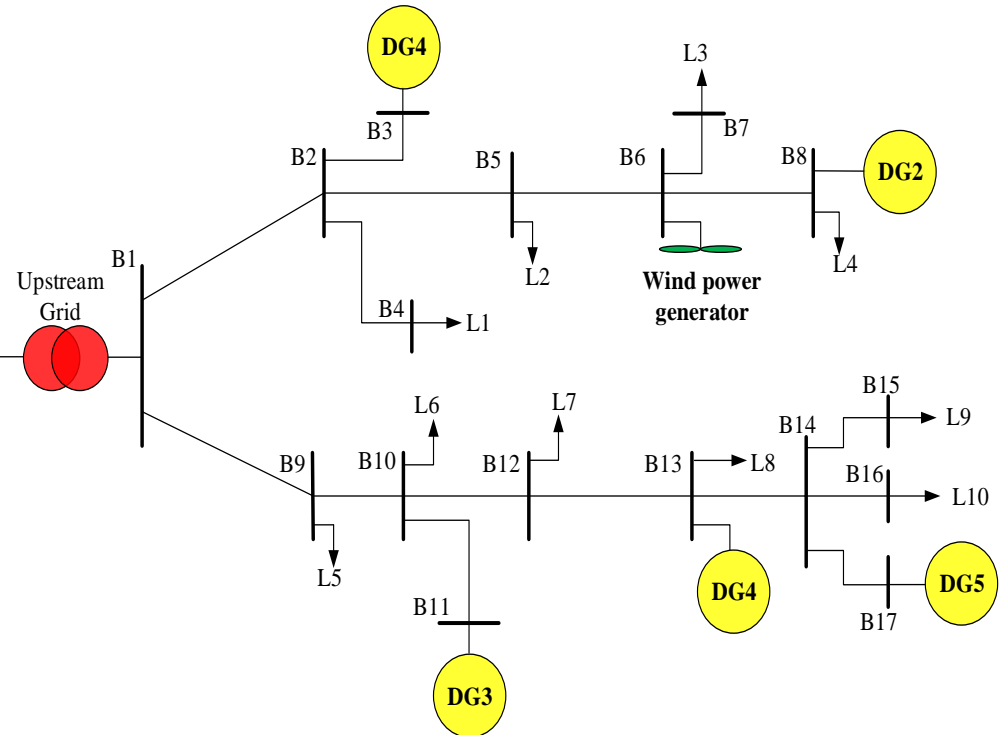
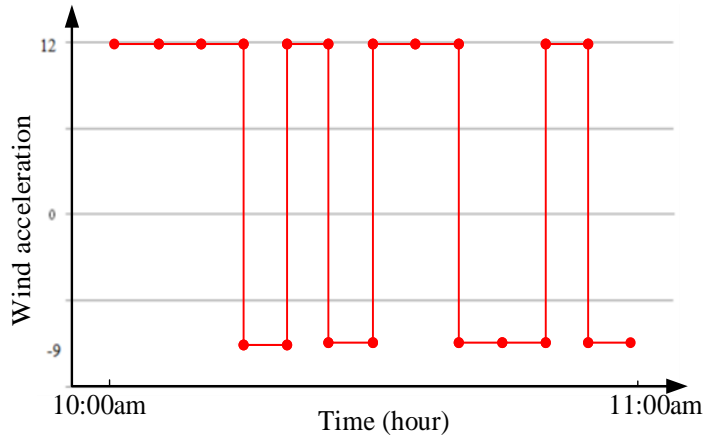
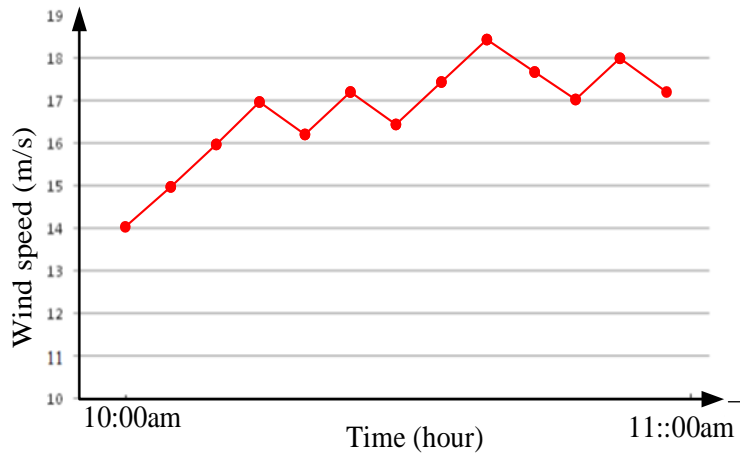
# Microgrid Operation

- Multiobjective Cost Function

$$\text{Min } SMCF = \sqrt{\beta \left( \frac{OC - OC^*}{OC^*} \right)^2 + \gamma \left( \frac{EL - EL^*}{EL^*} \right)^2 + \mu \left( \frac{VPD - VPD^*}{VPD^*} \right)^2}$$

- where  $OC^*$ ,  $EL^*$ , and  $VPD^*$  are the minimum accessible values for OC, EL, and VPD.
- Parameters  $\beta$ ,  $\gamma$ , and  $\mu$  are weighting factors adjusting the impact of different terms in the objective.

# Case Study



# Case Study

$$f_+ = 4$$

$$f_- = 4$$

$$a_+ = 12$$

$$a_- = 9$$

- Applying the DMN model, the expected wind acceleration is +1.5.
- The wind speed is in overall speed increasing class.
- The expected wind speed is calculated to be 14.75 (m/s).
- Using the power curve of the wind turbine, the power provided by this renewable generation source is 1.5 MW.

# Case Study

## Bus Voltage and Active of the MG

Bus No.	Voltage (p.u.)	Angle (rad/sec)
B1	1.06	0.000
B2	1.00	-0.059
B3	1.04	-0.047
B4	0.96	-0.105
B5	0.96	-0.059
B6	1.01	0.025
B7	1.01	-0.030
B8	1.04	-0.056
B9	0.99	-0.081
B10	0.99	-0.073
B11	1.02	-0.030
B12	1.00	-0.072
B13	1.06	-0.028
B14	1.00	-0.041
B15	0.96	-0.080
B16	0.96	-0.089
B17	1.05	0.029

## Active and Reactive Power produced by Generation Sources

Gen. Sources	P (MW)	Q (MVar)
Upstream Grid	1.53	0.30
DG1	0.31	0.88
DG2	1.12	0.01
DG3	0.49	1.08
DG4	2.48	0.18
DG5	0.75	1.07
Wind turbine	1.50	-1.10

## Objective functions value

Operating cost	Energy loss	Voltage profile deviation index
\$6312	372 KW	0.028

# Conclusion

- DMN technique can be applied to model wind power fluctuation in hour-ahead system scheduling.
- Actual forecasted wind speed is modeled in the OPF.
- DMN can model the uncertainty when there is no access to PDF of the uncertain variable.
- This method provide only one scenario for wind speed.
- As the future works, DMN technique can be applied to forecast wind speed, and the state of the system during the future operation hours.

Thank you!